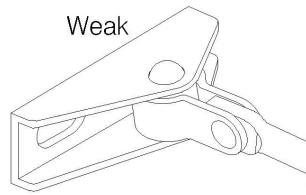


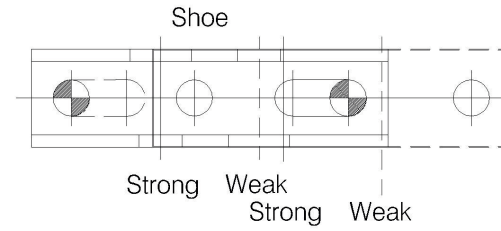
Strong

Position 1 force 3
Position 2 force 4



Weak

Position 1 force 2
Position 2 force 3



Shoe

DETERMINE POSITION OF SHOE FROM CHART OPPOSITE AND FIX ACCORDINGLY

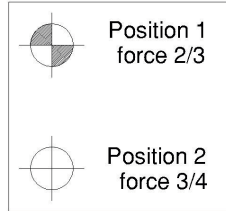
UNDERSIDE OF FRAME



SET TO TOP OF DOOR



Speed Adjusting Valve

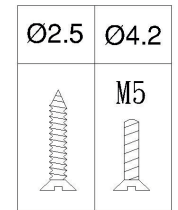


Position 1
force 2/3

Position 2
force 3/4

6-M5*P0.8

Use the side of template for anti-clockwise opening door
(RIGHT HAND OPENING DOOR)

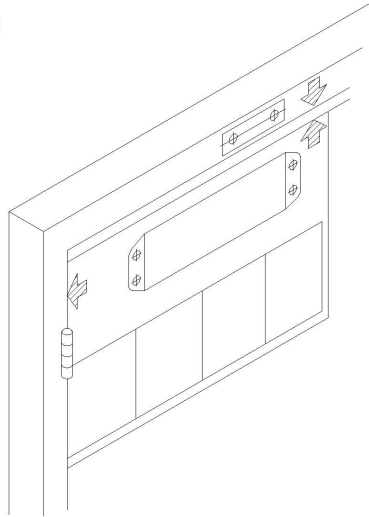


HINGE EDGE OF DOOR

(Position 1)force 2/3 90mm

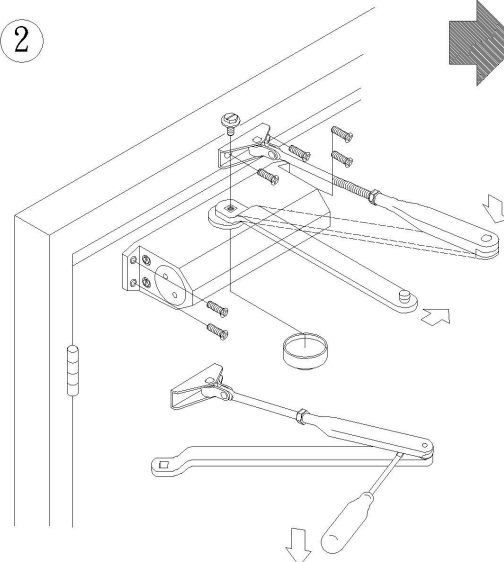
(Position 2)force 3/4 110mm

1



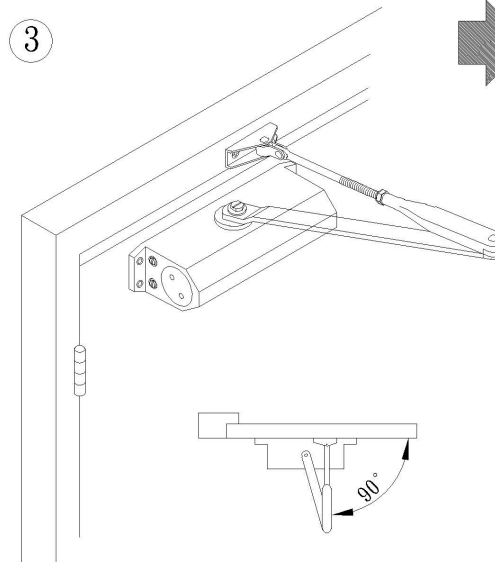
" Determine opening degree requirements 105 or 180 degrees, then select power requirement. This can be located on the template. Then use template to mark holes for closer body and arm pivot bracket.

2



" Arm pivot bracket assembly into position and fix closer body to the marked holes ensuring that you select the position of the shoe, on the face of the frame, in the correct direction " Refer weak or strong.

3

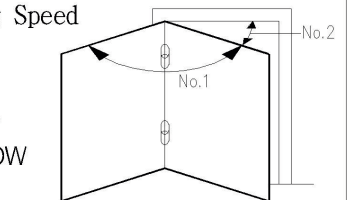
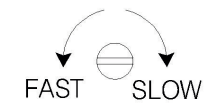


Standard drawing

4

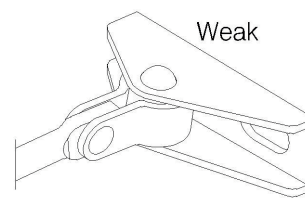
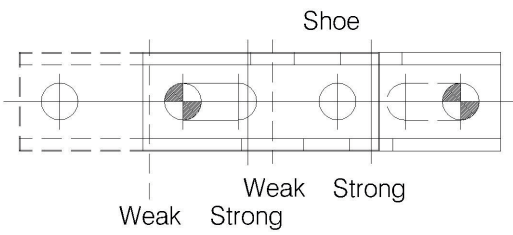
No. 1 Closing Speed

No. 2 Latching Speed



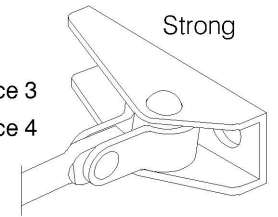
Adjust speed

DETERMINE POSITION OF SHOE FROM CHART OPPOSITE AND FIX ACCORDINGLY



Position 1 force 2
Position 2 force 3

Position 1 force 3
Position 2 force 4



UNDERSIDE OF FRAME

SET TO TOP OF DOOR

